

# Key concepts

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- Different types of dynamic loads (responses)
- Functions (loads or responses) of arbitrary complexity may be modelled as linear sums of sines and cosines.
- Fourier Transform and why we use it.
- Discrete-time Fourier Transform

Lecture 1: Dynamic loads and response













#### The time-frequency duality: a matter of perspective

- Time  $\leftarrow \rightarrow$  frequency
- 2 ways of looking at a structural response/load that are interchangeable
- No information is lost in changing from one to the other (in principle).
- The advantage is that changing the perspective the solution to a dynamic problem can become simpler and/or clearer (we will see this in our last lecture)

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#### The time domain

- The traditional way of observing phenomena (loads, responses)
- Is a record of what happens to a given parameter versus time
- Issues with measuring it:
  - Period : long enough
  - Amplitude : large enough
  - Force : strong enough
  - Indirect measurement : signals

## The frequency domain

- By adding up sine waves we can generate any waveform that exists in the real world
- By picking the amplitudes, frequencies and phases correctly we can (in theory) reproduce it identically
- The same applies the other way round: a real world signal (load or response history) can be broken down into a series of sine waves



Representation of dynamic loads as harmonics

$$g(t) = A\sin(2\pi v t + \phi)$$

• A is the amplitude

- $\nu$  is the frequency measured in cycles per second
- $\phi$  is the phase (responsible for getting values other than 0 at t = 0)
- $\omega=2\pi\nu$  is the circular frequency measured in radians per second
- In addition, we can define period as  $T=1/\nu$  , the inverse of the frequency

#### Representation of dynamic loads as harmonics

• Any periodic function (load) can be represented as a linear combination of sines and cosines

$$f(t) = A_0 + \sum_{k=1}^{n} \left( A_k \cos(2\pi\nu_k t) + B_k \sin(2\pi\nu_k t) \right)$$

















#### **The Fourier Transform**

The **Fourier Transform** of a function in the time domain f(t) is defined as:

$$F(v) = \int_{-\infty}^{\infty} f(t) e^{-2\pi i v t} dt$$

while the **Inverse Fourier Transform** of a function in the frequency domain F(v), is:

$$f(t) = \int_{-\infty}^{\infty} F(v) e^{2\pi i v t} dv$$









### The Fourier Transform

#### Properties

Property	f(t)	$F(\nu)$
1. Linearity	$af_1(t) + bf_2(t)$	$aF_1(\nu) + bF_2(\nu)$
2. Convolution theorem	$f_1(t) * f_2(t)$	$F_1(\nu)F_2(\nu)$
3. Product theorem	$f_1(t)f_2(t)$	$F_1(\nu) * F_2(\nu)$
4. Time shifting	$f(t-t_0)$	$F(\nu)e^{-2\pi i\nu t_0}$
5. Frequency shifting	$f(t)e^{-2\pi i\nu_0 t}$	$F(\nu - \nu_0)$
6. Scaling	f(at)	$ a ^{-1}F(\nu/a)$

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 The frequency domain: a familiar domain

 Image: Constant of the frequency domain of the frequency domain of the frequency domain of the frequency examples

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The Discrete-time Fourier Transform

The DTFT:

$$X(e^{i\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-i\omega n}$$

• The synthesis equation:

$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(e^{i\omega}) e^{i\omega n} d\omega$$

# The Discrete-time Fourier Transform

- The main differences between discrete-time and continuous -time FT:
  - Periodicity of the DFT
  - Finite interval of integration of the synthesis equation

# Fast Fourier Transform (FFT) Algorithm



James W. Cooley, IBM



https://www.youtube.com/watch?v=iTMn0Kt18tg.

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